

# TOPOLOGICAL APPROACHES TO EPISTEMIC LOGIC

## Lecture 1: Motivation and Topological Preliminaries

Aybüke Özgün

ILLC, University of Amsterdam

Tsinghua Logic Summer School  
14.07.2025

# Contents

Course Introduction

Motivation & (a Brief) Introduction to Epistemic Logic

Topological Preliminaries

# Contact Information

**Course Website:** <http://tsinghualogic.net/JRC/topological-approaches-to-epistemic-logic/>

All course material will be posted here! We will also post updates on the WeChat group.

**Lecturer:** Aybüke Özgün

**email:** [a.ozgun@uva.nl](mailto:a.ozgun@uva.nl)

**website:** <https://sites.google.com/site/ozgunaybuke/>

**Teaching Assistants:**

- ▶ Yumin Ji ([m2e07@naver.com](mailto:m2e07@naver.com))
- ▶ Wenfei Ouyang ([oywf23@mails.tsinghua.edu.cn](mailto:oywf23@mails.tsinghua.edu.cn))

## For questions

- ▶ For practical questions you can use WeChat.
- ▶ For content related questions, please send an email to [a.ozgun@uva.nl](mailto:a.ozgun@uva.nl) or Yumin or Wenfei, or just ask me after the lectures.

# Prerequisites

- ▶ Basic knowledge of modal logic and a reasonable level of mathematical maturity.
  - ▶ Relational/Kripke semantics for modal logic
  - ▶ Soundness & completeness
- ▶ No background in topology is necessary: all the required topological notions will be introduced in the course.
- ▶ Some knowledge of and interest in (dynamic) epistemic logic is advantageous but not required.

# Course Structure

- ▶ 45 min + 5 min break + 45 min + 15 min break + 45 min.
- ▶ There will be 3 homework and a take-home exam.

# Assessment

- ▶ each homework: 20% (homeworks in total = 60%)
- ▶ take-home exam: 40%

# Deadlines

- ▶ Homework 1: July 16, 13h00
- ▶ Homework 2: July 17, 13h00
- ▶ Homework 3: July 18, 13h00
- ▶ Take-home exam: July 20, midnight



# Homework vs Practise Questions

- ▶ Homework *\*is graded\** and part of your final grade.
- ▶ Practise questions are *\*not\** to be submitted or graded.
- ▶ Practise questions are for you to solve more exercises. They will be given on slides or in the handout.
- ▶ Students are encouraged to work on the practise questions together. *Homework should be done individually and independently.*

# Course Materials - General Sources

- ▶ Any book on introduction to general topology. Some options:

Engelking, R. (1989) *General Topology*, volume 6.  
Heldermann Verlag, Berlin, second edition.

Dugundji, J. (1965) *Topology*. Allyn and Bacon Series in  
Advanced Mathematics. Prentice Hall.

- ▶ Modal Logic

Blackburn P, Rijke M de, Venema Y. (2001) *Modal Logic*.  
Cambridge University Press.

- ▶ Modal Logics for Topology

van Benthem, J. and Bezhanishvili, G. (2007). Modal logics  
of space. In *Handbook of Spatial Logics*, pages 217-298.  
Springer Verlag.

## Course Materials - More...

- ▶ A number of research papers and dissertation chapters.
- ▶ I will use slides during lectures.
- ▶ Handout with the background information.

All course material will be made available on the course website.

# Tentative Outline

Day 1: Motivation and Topological Preliminaries

Day 2: Topological Semantics for Modal Logic

Day 3: Topological Evidence Models

Day 4: Subset Space Semantics and Topo-Logic

Day 5: Overview of Selected Topics and Summary

# Contents

Course Introduction

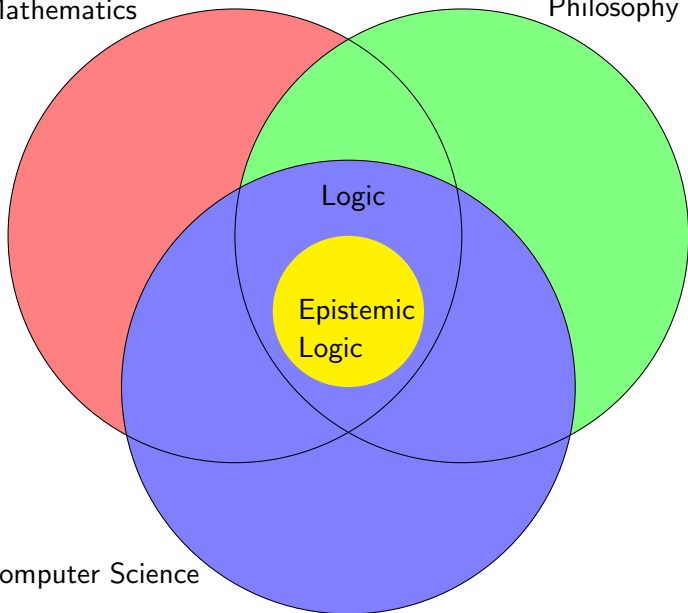
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Topological Preliminaries

Mathematics

Philosophy

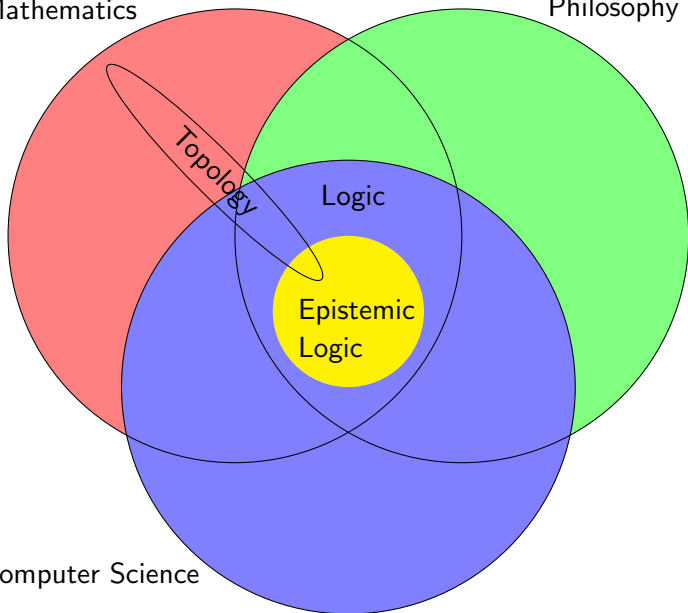
Computer Science



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# Epistemic Logic

**Epistemic Logic** is an umbrella term for a variety of *(modal) logics* whose main objects of study are knowledge, belief, and related notions.<sup>1</sup>

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# Epistemic Logic

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By using a modal language defined recursively as

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid \varphi \vee \varphi \mid \varphi \rightarrow \varphi \mid K\varphi \mid B\varphi$$

we can state various properties about the notions of knowledge, belief, and their relationships.

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**Note:**  $\varphi \vee \psi := \neg(\neg\varphi \wedge \neg\psi)$  and  $\varphi \rightarrow \psi := \neg\varphi \vee \psi$

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# Epistemic Logic

$K\varphi$  := the agent knows that  $\varphi$ .

$B\varphi$  := the agent believes that  $\varphi$ .

*"I know/believe that I am taller than 1.6m."*

# Epistemic Logic

For example, we can state:

$$K\varphi \rightarrow \varphi$$

*"If the agent knows  $\varphi$ , then  $\varphi$  is true."*

$$K\varphi \rightarrow B\varphi$$

*"If the agent knows  $\varphi$ , then they believe  $\varphi$ ."*

$$B\varphi \rightarrow BK\varphi$$

*"If the agent believes  $\varphi$ , then they believe that they know  $\varphi$ ."*

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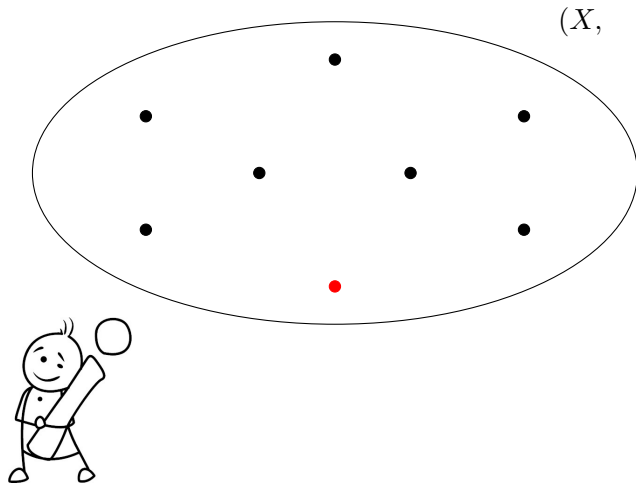
- ▶ *talk only about knowledge and belief*
- ▶ *talk about evidential basis of knowledge and belief*
- ▶ *talk about awareness, limits of cognitive and computational capacities...*

# Models of Epistemic Logic: Hintikka Style

The standard approach to epistemic logic formalizes **knowledge** and **belief** based on the relational possible worlds models.

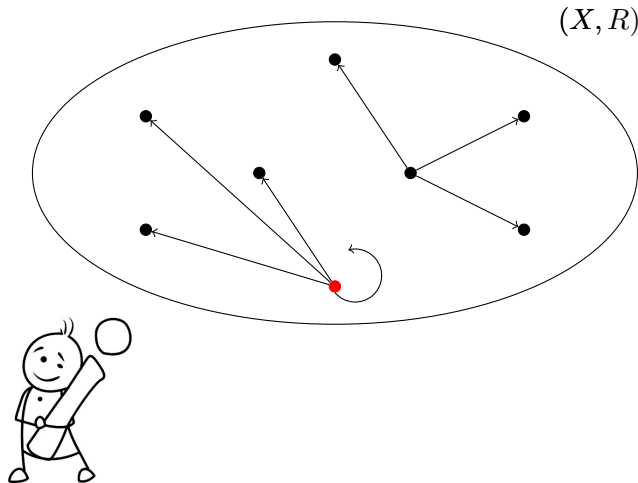
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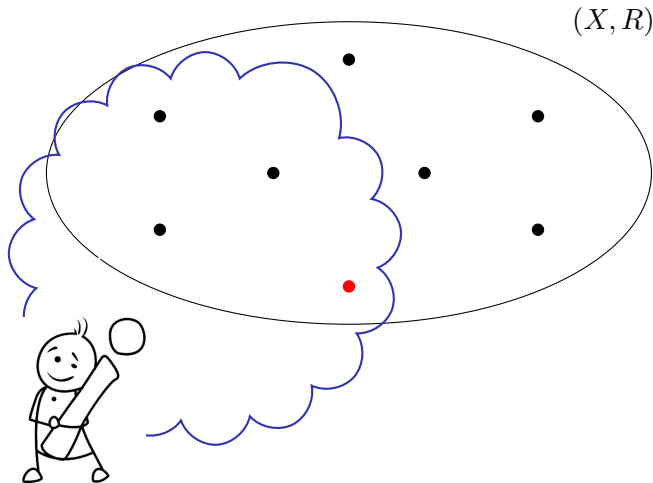
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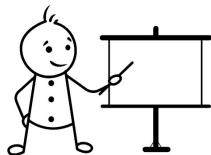
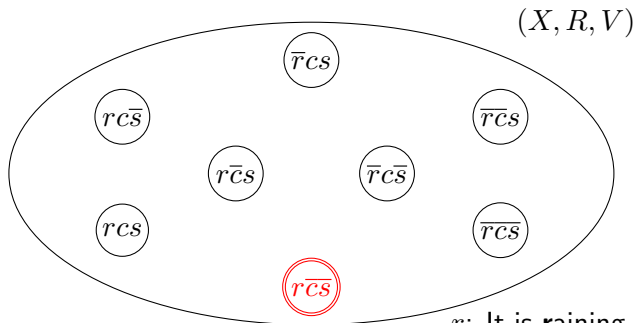
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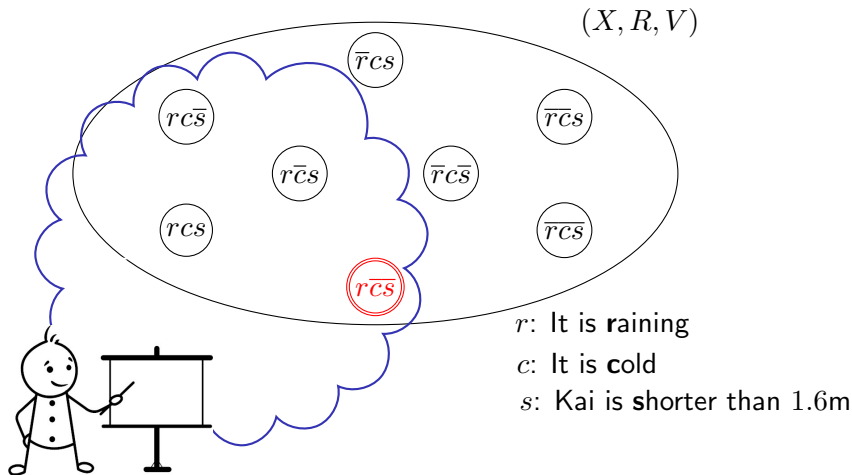


$r$ : It is **r**aining  
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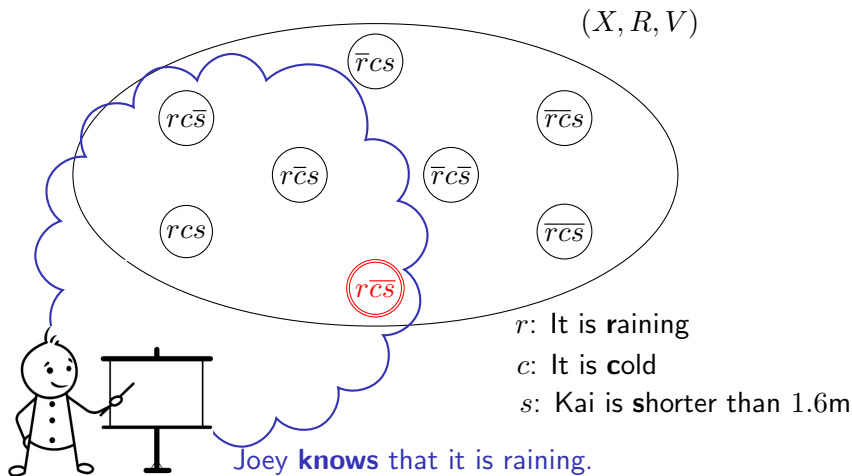
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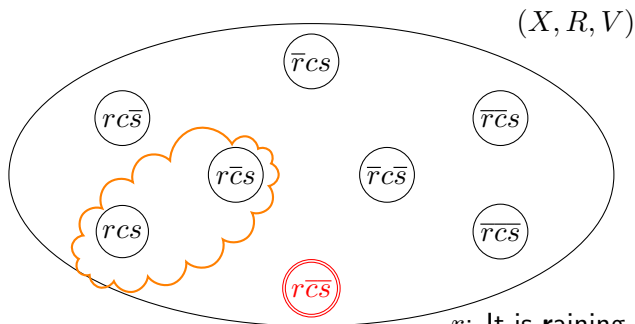
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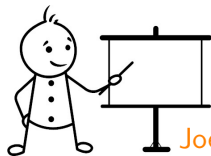
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Joey **believes** that Kai is shorter than 1.6m.

# Normal Epistemic Logics - Hintikka Style



## Definition (Relational (Kripke) Frame/Model)

A *relational frame* is a pair  $\mathcal{F} = (X, R)$ , where

- ▶  $X$  is a non-empty set of possible worlds, and
- ▶  $R$  is a binary relation on  $X$ , i.e.,  $R \subseteq X \times X$ .

A *relational model* is a tuple  $\mathcal{M} = (X, R, V)$ , where  $(X, R)$  is a Kripke frame and  $V : \text{Prop} \rightarrow \mathcal{P}(X)$  is a valuation map.

Given a Kripke model  $\mathcal{M} = (X, R, V)$  and a possible world  $x \in X$ , the pair  $(\mathcal{M}, x)$  is called a *pointed model*.

# Normal Epistemic Logics - Hintikka Style

Given a Kripke model  $\mathcal{M} = (X, R, V)$ :

- ▶ *possible worlds* represent the ways the world could be or could have been. They are *complete* and *consistent*. One of the worlds in  $X$  represents the *actual world*.
- ▶  $R$  is called the *accessibility* or *indistinguishability* relation.  
 $xRy :=$  *the agent cannot distinguish  $y$  from  $x$  (when in  $x$ ).*
- ▶  $V(p)$  is the set of all possible worlds in the model where  $p$  is true.

# Normal Epistemic Logics - Hintikka Style

Recall the language of epistemic logic  $\mathcal{L}_K$ :<sup>2</sup>

$$\varphi ::= p \mid \neg\varphi \mid \varphi \wedge \varphi \mid K\varphi$$

## Definition (Relational Semantics)

Given a Kripke model  $\mathcal{M} = (X, R, V)$  and a state  $x \in X$ , *truth* of a formula in the language  $\mathcal{L}_K$  is defined recursively as follows:

$\mathcal{M}, x \models p$       iff       $x \in V(p)$ , where  $p \in \text{Prop}$

$\mathcal{M}, x \models \neg\varphi$       iff      not  $\mathcal{M}, x \models \varphi$

$\mathcal{M}, x \models \varphi \wedge \psi$       iff       $\mathcal{M}, x \models \varphi$  and  $\mathcal{M}, x \models \psi$

$\mathcal{M}, x \models K\varphi$       iff      for all  $y \in X$ , if  $xRy$  then  $\mathcal{M}, y \models \varphi$ .

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<sup>2</sup>In the handout in Section 1.1, we use  $\Box$  instead of  $K$ . This is only a notational change, the frameworks are the same.

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$\mathcal{M}, x \models K\varphi$	iff	for all $y \in X$ , if $xRy$ then $\mathcal{M}, y \models \varphi$ .

In other words:  $\varphi$  is *known/believed at  $w$*  iff it is true at every possible world that is epistemically indistinguishable from  $w$ .

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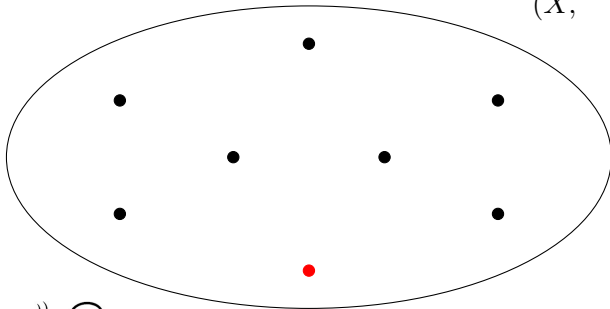
**Knowledge/Belief = truth in all epistemically possible worlds**

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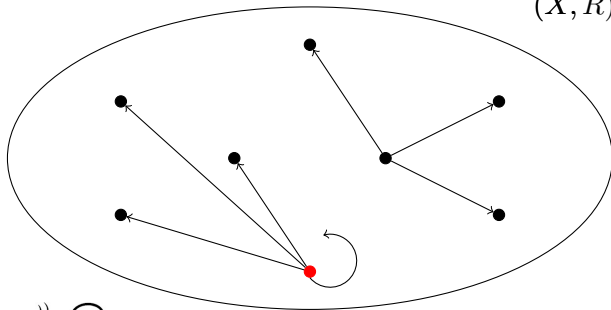
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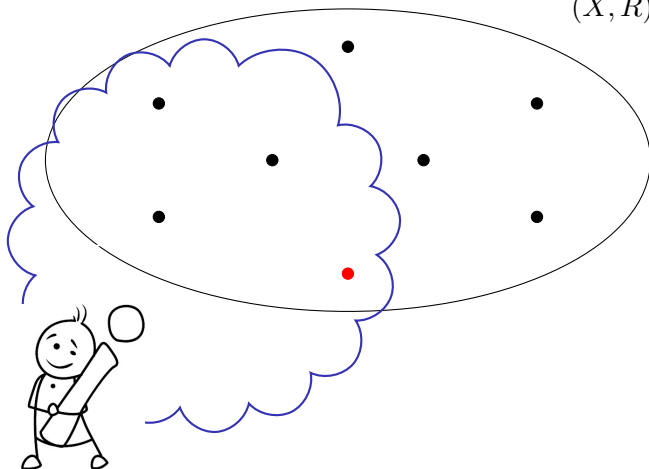
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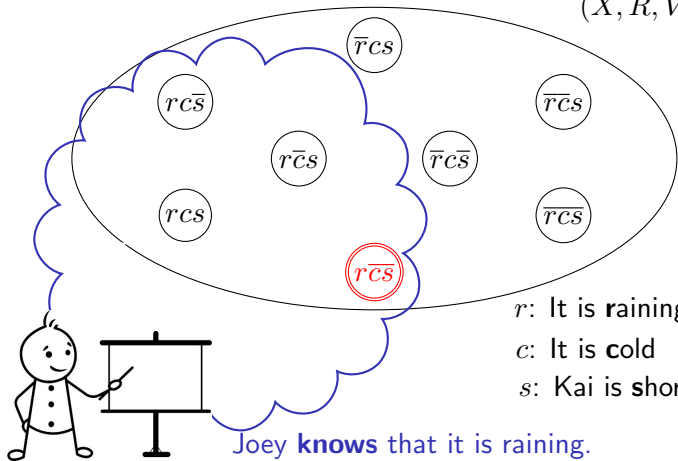
$(X, R)$



$(X, R)$



$(X, R, V)$



# Hintikka Style Epistemic Logic

## Pros

- (+) relatively easy
- (+) well-developed model theory
- (+) works well for, e.g., derivative attitudes such as
  - ▶ what *one ought to know* given what one knows,
  - ▶ what one can *potentially derive* from one's given body of information.

# Hintikka Style Epistemic Logic

## Cons

- (–) not rich enough to talk about evidence (and further evidence acquisition)
  - ★ *How to represent evidence?*
  - ★ *How does evidence relate to knowledge, belief and justification?*
  - ★ *How to represent learning after having acquired further evidence?*
- (–) models idealized agents (without cognitive, computational, and conceptual limits)
  - ★ *How to model non-ideal but logically competent reasoners?*

# Hintikka Style Epistemic Logic

## Cons

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- (-) ~~models idealized agents (without cognitive, computational, and conceptual limits)~~ ⇒ Another course!
  - ★ ~~How to model non-ideal but logically competent reasoners?~~

# Epistemic Logic vs. Topology



# Epistemic Logic vs. Topology

**Epistemic Logic** is an umbrella term for a variety of (*modal*) *logics* whose main objects of study are knowledge, belief, and related notions.

**Topology** is the abstract mathematical study of geometric structures that are unaltered by elastic change of shapes and sizes.

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# Epistemic Logic & Topology

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# Epistemic Logic & Topology

★ *What can Topology do for Epistemic Logic?* **A lot...**

*measurement/observation, argument, justification, belief, knowledge...*

$\approx$

open, close, dense, nowhere dense sets, interior, closure, derivative...

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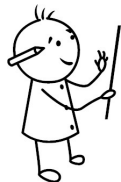
We can employ topological tools to:

- ▶ represent infallible, factive, false, misleading evidence,
- ▶ distinguish current evidence from potential evidence,
- ▶ study knowledge, knowability, and belief.
- ▶ formalize verifiability, falsifiability, and inductive learnability...

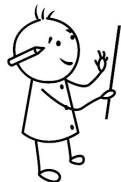
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Joey believes that Kai is shorter than 1.6m,



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Joey **believes** that Kai is shorter than 1.6m, because Joey has taken many measurements with different devices: none of them contradicts Joey's claim and some support it.

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$m_1 = (1.45, 1.55),$

$m_2 = (1.35, 1.50),$

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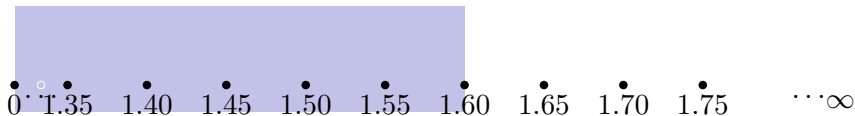
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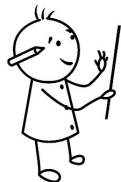
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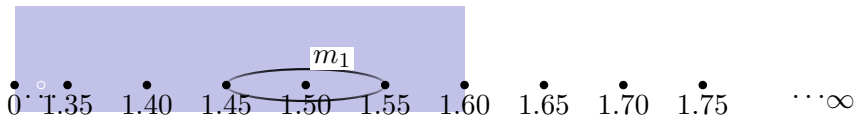
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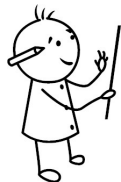
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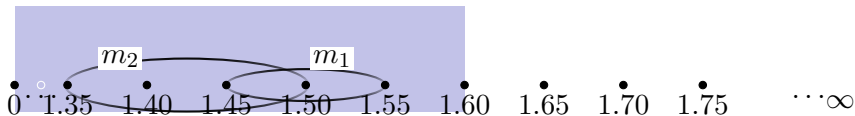
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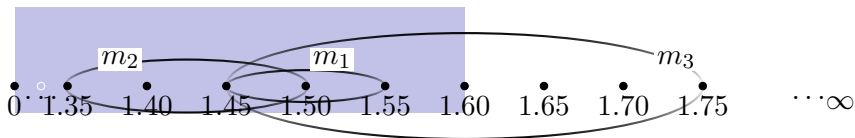
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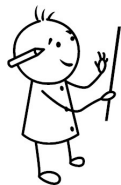
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$$S = (0, 1.60)$$



# Topology as Information Structures



Joey *believes* that Kai is shorter than 1.6m, because Joey has taken many measurements with different devices: none of them contradicts Joey's claim and some support it.

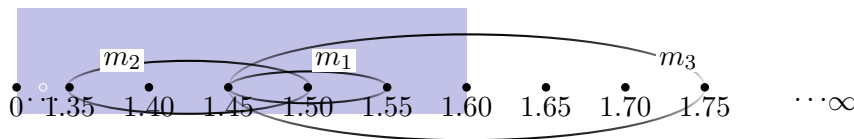
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This situation can easily be formalized on the real number line  $\mathbb{R}$ .

# Topology as Information Structures

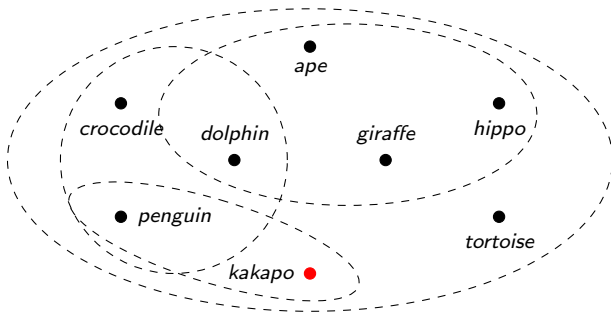


Joey is an evolutionary biologist, investigating an animal fossil. He receives pieces of evidence from three sources (from colleagues or experiments):

$e_1$ : it is a mammal

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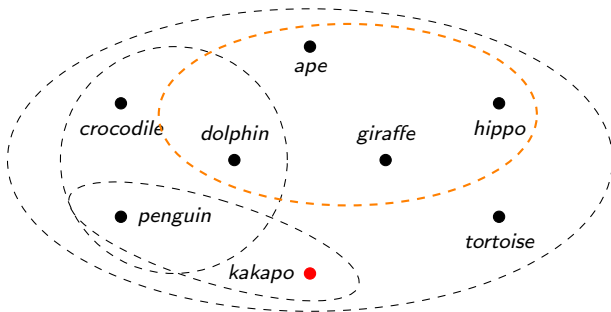


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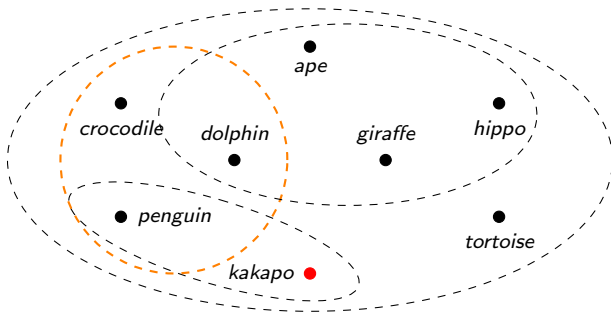


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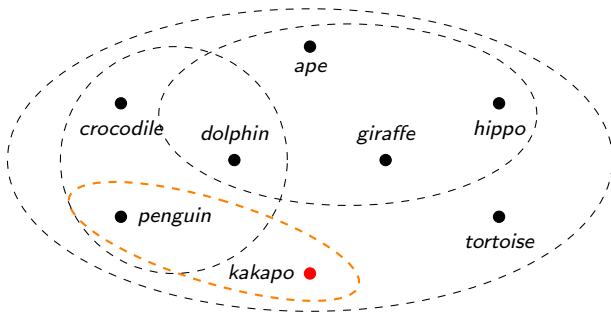


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★ *How can Joey form consistent beliefs based on their evidence?*

# Contents

Course Introduction

Motivation & (a Brief) Introduction to Epistemic Logic

Topological Preliminaries



# Topological Spaces

A *topological space* is a pair  $(X, \tau)$ , where  $X$  is a nonempty set and  $\tau \subseteq \mathcal{P}(X)$  is a family of subsets of  $X$  such that

1.  $\emptyset \in \tau$  and  $X \in \tau$ ;
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Example:  $X = \{1, 2, 3\}$  and  $\tau = \{\emptyset, \{1\}, \{1, 2\}, \{1, 2, 3\}\}$ .

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Non-example:  $X = \{1, 2, 3\}$  and  $\tau = \{\emptyset, \{1\}, \{2\}, \{1, 2, 3\}\}$

Why?

# Topological Spaces - Terminology

- ▶  $(X, \tau)$  is the *topological space*,
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Can you think of a set that is a clopen in all topologies?

# Neighborhoods, interior points, limit points

Given a topological space  $(X, \tau)$ :

A(n) *(open) neighborhood* of a point  $x \in X$  is an open set  $U \in \tau$  with  $x \in U$ .

An *interior point* of a set  $A \subseteq X$  is a point  $x \in X$  s.t. there exists a neighborhood  $U$  of  $x$  with  $U \subseteq A$ .

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**Fact 1.**  $\text{Int}(A)$  is an open set and is the *largest open subset of  $A$* , that is

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$$\text{Cl}(A) = \{x \in X \mid \forall U \in \tau (x \in U \Rightarrow U \cap A \neq \emptyset)\}$$

**Fact 2.**  $\text{Cl}(A)$  is *the smallest closed set containing  $A$* , that is

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**Fact 3.**  $\text{Cl}(A) = X \setminus \text{Int}(X \setminus A)$  for all  $A \subseteq X$ . (Prove this!)

## Derivative and co-derivative

A *limit point* of a set  $A$  is a point  $x \in X$  s.t. every neighborhood  $U$  of  $x$  contains a point  $y \in A$  with  $y \neq x$ .

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The *(Cantor) derivative of  $A$*  is the set of its limit points:

$$d(A) = \{x \in X \mid \forall U \in \tau(x \in U \Rightarrow (U \setminus \{x\}) \cap A \neq \emptyset)\}$$

The *co-derivative of  $A$*

$$t(A) = X \setminus d(X \setminus A) = \{x \in X \mid \exists U \in \tau(x \in U \subseteq A \cup \{x\})\}$$

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An *isolated point of  $A$*  is a point  $x \in A \setminus d(A)$ ; in other words, a point in  $A$  that is **not** a limit point of  $A$ .

## Alternative Notations

$\overline{A}$  for closure  $Cl(A)$ ,  
 $A'$  for derivative  $d(A)$ .

## Examples

1. In the standard topology on  $\mathbb{R}$ ,  $\text{Int}([0, 1]) = (0, 1)$  and  $\text{Cl}((3, 4)) = [3, 4]$ .

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6. In any discrete topology  $(X, \mathcal{P}(X))$ ,  $d(A) = \emptyset$  for all  $A \subseteq X$  (Prove this!)

## Properties of $Int$ and $Cl$

The closure operator  $Cl$  of any topological space  $(X, \tau)$  satisfies the so-called *Kuratowski properties/axioms*:

1.  $Cl(\emptyset) = \emptyset$
2.  $A \subseteq Cl(A)$  for all  $A \subseteq X$
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A Kuratowski closure operator is an alternative to the standard definition of topology:

for any Kuratowski closure operator  $Cl : \mathcal{P}(X) \rightarrow \mathcal{P}(X)$ ,  
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Prove this!

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The interior satisfies the dual properties:

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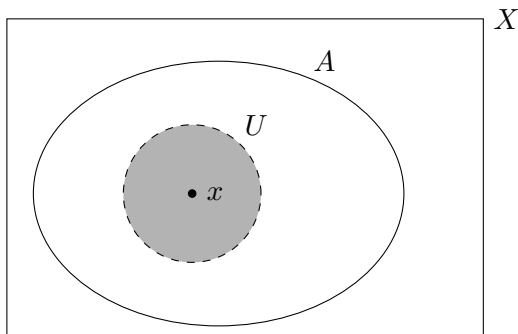
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Prove this!



# Epistemic interpretations



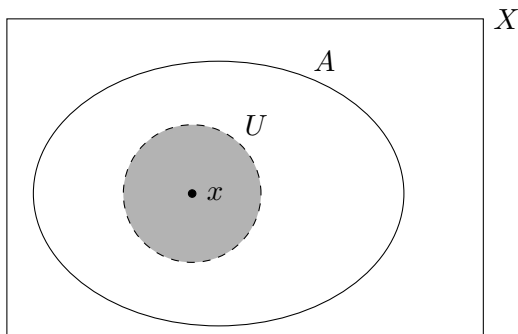
Think of  $U$  as a piece of evidence that (imperfectly) indicates the true state of the world: the points in  $U$  are precisely those that are compatible with the evidence.

E.g.,  $U$  might be the result of some measurement with error.

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<sup>2</sup>Special thanks to Adam Bjorndahl for this slide.

## Epistemic interpretations



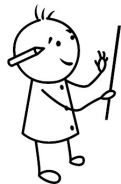
Such a “measurement”  $U$  is not precise enough to tell you the exact state of the world.

However, it can still be informative: in the above, it is precise enough to indicate that  $A$  holds.

---

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# Topology as Information Structures



Joey **believes** that Kai is shorter than 1.6m, because they have taken many measurements with different devices: none of them contradicts their claim and some support it.

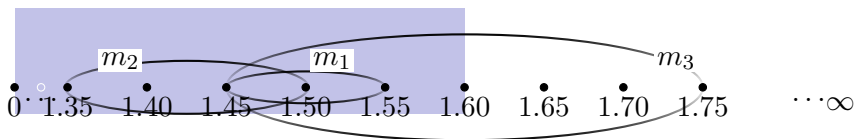
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$$m_1 = (1.45, 1.55),$$

$$m_2 = (1.35, 1.50),$$

$$m_3 = (1.45, 1.75).$$

$$S = (0, 1.60)$$



This situation can easily be formalized on the real number line  $\mathbb{R}$ .

# Epistemic interpretations

Open sets as *verifiable properties*: one for which there is evidence, whenever it is true.

Closed sets as *falsifiable property*: one against which there is evidence, whenever it is false.

Read  $Int(A)$  as '*A is known (or knowable)*' based on evidence.

Read  $CI(A)$  as '*A is epistemically possible*' (compatible with all evidence).

# Epistemic interpretations

$$Int(X) = X$$

$$Int(A) \subseteq A$$

$$Int(A \cap B) = Int(A) \cap Int(B)$$

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Tautologies are known/knowable

Factivity of Knowledge/ability

Dist. over Conjunction

Positive Introspection

